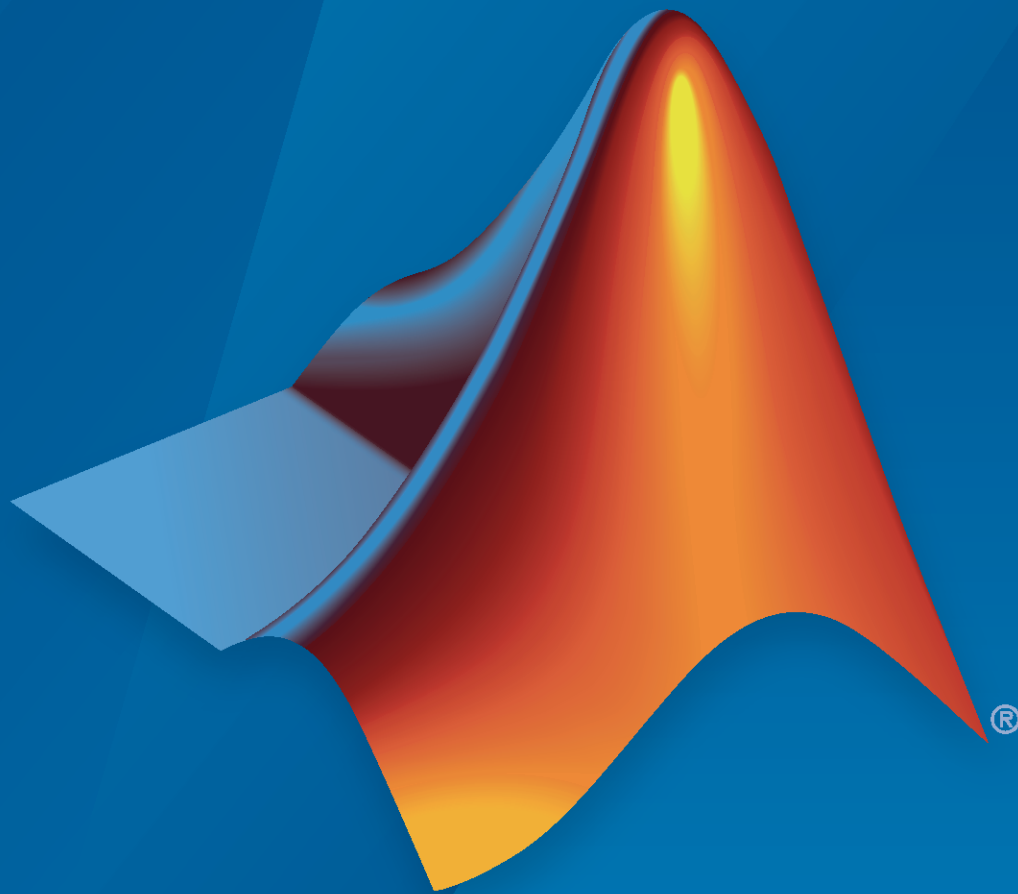


Simulink® Real-Time™

R2020b & Later Upgrade User's Guide



MATLAB® & SIMULINK®

R2021b



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The MathWorks, Inc.
1 Apple Hill Drive
Natick, MA 01760-2098

Simulink® Real-Time™ R2020b & Later Upgrade User's Guide

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September 2020	Online only	New for Version 7.0 (Release 2020b)
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Upgrade Systems and Models for Release R2020b

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Upgrade Systems and Models for Release R2020b

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Check model for upgradable Simulink Real-Time features

Check ID: `mathworks.design.slrealtimeUpgrades`

Check the model for Simulink Real-Time features from a previous release that require an upgrade for compatibility with the current release.

Description

This check identifies upgradable Simulink Real-Time features and upgrades the features where possible and recommends manual upgrades when needed. Block forwarding in the `slrealtime` library and the Speedgoat I/O Blockset eases the upgrade process.

Results and Recommended Actions

Condition	Recommended Action
System Target File upgrade	Change the System Target File to <code>slrealtime.tlc</code> .
Simulink Real-Time block upgrades	Upgrades blocks when possible. Identifies blocks for manual upgrade when needed.
Signal Upgrades	Upgrades signals for Instrument object compatibility.
Simulink Real-Time configuration parameter upgrades	Upgrades configuration parameters for toolchain build and real-time application options.

Capabilities and Limitations

You can:

- Run this check on your Simulink Real-Time models from release R2020a and previous releases.

See Also

- “Troubleshoot Model Upgrade for R2020b” on page 1-3
- “Troubleshoot System Upgrade for R2020b” on page 1-5

Troubleshoot Model Upgrade for R2020b

When I build my pre-R2020b Simulink Real-Time models in R2020b, I get build errors. Some of the blocks in my model have the label **Obsolete Simulink Real-Time Block**.

What This Issue Means

For R2020b, you must upgrade the Simulink Real-Time model. A model Upgrade Advisor check is available to support this upgrade.

Try This Workaround

To upgrade your model for Simulink Real-Time R2020b features, use this software upgrade process:

- 1 Install Simulink Real-Time and other required products.
- 2 Install the Simulink Real-Time Target Support Package by using the MATLAB **Add-Ons** menu.
- 3 Install the Speedgoat I/O Blockset. Go to the Speedgoat website.
- 4 Upgrade the target machine software. See “Troubleshoot System Upgrade for R2020b” on page 1-5.
- 5 Open a R2020b or earlier Simulink Real-Time model.
- 6 Run the **Upgrade Advisor**. On the **Modeling** tab, select **Model Advisor > Upgrade Advisor**.
- 7 In the Upgrade Advisor dialog box, select **Check model for upgradable Simulink Real-Time features**. Click the **Run This Check** button. The advisor lists the upgrades that it can apply and the upgrades that require manual changes.
- 8 After the check, click the **Upgrade** button. The advisor upgrades the model by applying all nonmanual changes.

Apply Manual Changes

When the Upgrade Advisor encounters model issues that it cannot resolve by using automated changes, the Upgrade Advisor reports these as **Warning: Some of the features require manual changes**. It is a good practice to copy the text of these warnings and save it for reference as you apply changes to your model.

Apply Speedgoat Utilities

In R2020b, Speedgoat software provides support for configuring interrupts and Ethernet communications.

To configure model interrupts, use a single block from the Speedgoat I/O Blockset. You can use this block for asynchronous subsystems or for triggering the base rate of the model. The list of available interrupt sources reflects the Speedgoat I/O Blockset blocks configured in the model. For more information see the block documentation in `speedgoatlib_utilities`.

To configure additional Ethernet ports on the target machine, the Speedgoat I/O Blockset provides a tool to configure these Ethernet ports. The configuration is specific to the target machine and reflects the labeling on the front plates of the target machine. For more information, in the MATLAB Command Window, type:

```
speedgoat.configureEthernet
```

See Also

“Troubleshoot System Upgrade for R2020b” on page 1-5

Troubleshoot System Upgrade for R2020b

I have upgraded my Simulink Real-Time software for R2020b and have installed the Simulink Real-Time Target Support Package. Now, I cannot download real-time applications to my target computer.

What This Issue Means

The upgrade for release R2020b requires software upgrades to the Simulink Real-Time software and the Speedgoat Target Machine software.

Try This Workaround

In R2020b, the change to a 64-bit POSIX compliant real-time operating system on the target computer requires a software upgrade for your Speedgoat real-time target machine. For this upgrade, the Speedgoat I/O Blockset provides an interactive tool. To retain compatibility with previous versions of MATLAB, you can choose to upgrade the target machine to a dual-boot system where you can select the operating system at startup. Or, you can upgrade the target machine to use only the new operating system. For the upgrade, you need a USB drive and the target machine needs a keyboard and a monitor.

To upgrade your software:

- 1 Install Simulink Real-Time and other required products.
- 2 Install the Simulink Real-Time Target Support Package by using the MATLAB **Add-Ons** menu.
- 3 Install the Speedgoat I/O Blockset. Go to the Speedgoat customer portal.
- 4 To start the target machine upgrade, in the MATLAB Command Window, type:

```
speedgoat.migrateTarget
```

For more information, go to the Speedgoat website.

See Also

More About

- “Troubleshoot Model Upgrade for R2020b” on page 1-3

Troubleshoot MATLAB API Call Upgrade for R2020b

In R2020b, many objects and functions in the Simulink Real-Time API changed.

What This Issue Means

MATLAB® m-scripts written by using the Simulink Real-Time API require updates to run in R2020b and later releases.

Try This Workaround

These tables identify Simulink Real-Time API changes in R2020 and identify new workflows. Use these tables to guide your updates to pre-R2020b m-scripts. For information about Simulink Real-Time in previous releases, see:

<https://www.mathworks.com/help/doc-archives.html>

Target Computer Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.Application object, ApplicationName property SimulinkRealTime.target object, Application property	Get name of real-time application.	Changed name	Use Target object, App
SimulinkRealTime.target object, Connected property value is 'Yes'.	Get communication status between development and target computers.	Changed name	Use Target object, Cor Use connect function t
close function	Close connection between development and target computers.	Changed name	Use disconnect funct
getDiskSpace function	Get free space and total space on the drive, in bytes.	Moved to Speedgoat API	Use speedgoat.getDi
load function	Download real-time application to target computer.	Unchanged	Use load function after object. The real-time ap automatically loaded as process.
reboot function	Restart target computer.	Unchanged	Use reboot function to computer in standalone supported boot modes a

Real-Time Execution Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.target object, CPUOverload property	Get CPU overload status.	Changed name	Use Target object, Target or ModelStatus properties.
SimulinkRealTime.target object, AvgTET property	Get average task execution time.	Changed name	Use Target object, ModelStatus property.
SimulinkRealTime.target object, ExecTime property	Get real-time application execution time.	Changed name	Use Target object, ModelStatus property.
SimulinkRealTime.target object, MaxTET property	Get maximum task execution time.	Changed name	Use Target object, ModelStatus property.
SimulinkRealTime.target object, MinTET property	Get minimum task execution time.	Changed name	Use Target object, ModelStatus property.
SimulinkRealTime.target object, SampleTime property	Get time between samples (step size).	Changed name	Use Target object, ModelStatus.TETInfo property.
start function	Start execution of real-time application on target computer.	Changed workflow	Use start function to start application and set real-time options.
SimulinkRealTime.target object, Status property	Get execution status of real-time application.	Changed workflow	Use Target object, ModelStatus.status function.
stop function	Stop execution of real-time application on target computer.	Unchanged	Use stop function.
SimulinkRealTime.target object, StopTime property	Get or set time when real-time application stops running.	Changed workflow	Get by using Target object, ModelStatus.StopTime using setStopTime function.
SimulinkRealTime.target object, TETLog property	Access storage in the MATLAB workspace for task execution time.	Changed workflow	Use slrtTETMonitor function.

Execution Profiler Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
getProfilerData function	Retrieve profile data object.	Unchanged	Use getProfilerData function before application.

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.target object, ProfilerStatus property	Get state of profiler.	Changed workflow	Use Target object, App. There are added proper
resetProfiler function	Reset profiling service state to Ready.	Unchanged	Use resetProfiler fu resets itself when you s application.
startProfiler function	Start profiling service on target computer.	Unchanged	Use startProfiler fu execution profiler before application.
stopProfiler function	Stop profiling service on target computer.	Changed limitation	Use stopProfiler fun stop at 1GB is eliminate

Parameter Tuning Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
setparam function	Change value of tunable parameter in real-time application.	Changed syntax	Use setparam function
getparam function	Read value of observable parameter in real-time application.	Changed syntax	Use getparam function
SimulinkRealTime.target object, NumParameters property	Get number of tunable parameters.	Changed workflow	Use Application obje function.
SimulinkRealTime.target object, Parameters property	Get list of tunable parameters.	Changed workflow	Use Application obje function.
SimulinkRealTime.target object, ShowParameters property	Set flag to display the list of parameters.	Changed workflow	Use Application obje function.

Signal Tracing Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
getsignal function	Get single numerical value of a signal.	Changed workflow	Use Instrument obje function.
SimulinkRealTime.target object, NumSignals property	Get number of observable signals.	Changed workflow	Use Application obje function.

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.target object, OutputLog property	Access storage in MATLAB workspace for output or Y-vector.	Changed workflow	Use Simulink model "Si parameter: set_param(bdroot,... 'SignalLogging','on'
SimulinkRealTime.target object, ShowSignals property	Set flag to display the list of signals.	Changed workflow	Use Application obje function.
SimulinkRealTime.target object, Signals property	Get list of observable signals.	Changed workflow	Use Application obje function.

Signal Logging Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
importLogData function	Import buffered logging data to the active session of the Simulation Data Inspector.	Replaced	Use list function and more information, see t object.

Instrumentation Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
addscope function	Create a scope of specified type.	Replaced	Use the Simulation Data Use File Log blocks inst Use Instrumentobject blocks.
getscope function	Return scope identified by scope number.	Replaced	Use the Simulation Data Use File Log blocks inst Use Instrumentobject blocks.

Ethernet and EtherCAT Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
Target Computer Settings provided information about Ethernet setup on target computer.	Configure Ethernet ports on target computer	Moved to Speedgoat API	Use speedgoat.conf function

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
<code>SimulinkRealTime.etherCAT.filterNotifications</code> function	Display EtherCAT notifications in human-readable format	Changed name	Use <code>slrealtime.EtherCATNotifications</code> function

Target Computer Settings Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
<code>SimulinkRealTime.getTargetSettings</code> function	Get target computer settings.	Changed name	Use <code>getTargetSettings</code>

See Also

“Check model for upgradable Simulink Real-Time features” on page 1-2

More About

- “Troubleshoot Model Upgrade for R2020b” on page 1-3
- “Troubleshoot System Upgrade for R2020b” on page 1-5

Troubleshoot S-Function Build Upgrade for R2020b

My pre-R2020b model uses S-Functions. When I migrated my model to the current release, I see this S-Function related message in the build log:

```
undefined reference to 'C function in S-Function'
```

What This Issue Means

In R2020b, the compiler for model builds changed from a Windows® compatible C compiler to the QNX® Neutrino® C++ compiler. To accommodate this change, update S-Function code for C++ compatibility.

Tip Fortran S-Functions are not supported in R2020b and later releases of Simulink Real-Time.

Try This Workaround

To update S-Function code for C++ compatibility, modify the declaration of the S-Function in the header file.

For example, update this C S-Function declaration:

```
void getAllDataMyFunction(short);
void myfunction_initialize(short, unsigned char*, short*);
void myfunction_terminate(short, int);
```

Updated the code to this C++ S-Function declaration:

```
#ifdef __cplusplus
extern "C" {
#endif

void getAllDataMyFunction(short);
void myfunction_initialize(short, unsigned char*, short*);
void myfunction_terminate(short, int);

#ifdef __cplusplus
}
#endif
```

Before building the updated code, remember to remove all artifacts from previous model builds.

See Also

More About

- “External Code Integration”

External Websites

- How to mix C and C++

